

ABSTRACT

In a manipulator-type robot of the present invention, a manipulator base contains a connection case for making cable connections to an external device. In the connection case, a signal-line connecting section for external connection is disposed on a predetermined signal line of a cable that is routed through the inside of the manipulator. The connection case contains, other than the aforementioned signal-line connecting section for making connections to the outside, an additional signal-line connecting section.